

Z transform pairs:

Z - TRANSFORM PAIRS

$$x[n] = \delta[n] \longrightarrow 1 \checkmark \quad |z| > 0$$

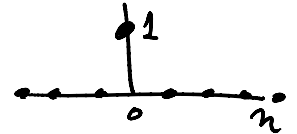
$$x[n] = \delta[n-n_0] \longrightarrow z^{-n_0} \checkmark \quad |z| > 0$$

$$x[n] = a^n u[n] \longrightarrow \frac{1}{1-az^{-1}}, \quad |z| > |a|$$

$$x[n] = -a^n u[-n-1] \longrightarrow \frac{1}{1-az^{-1}}, \quad |z| < |a|$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$x[n] = \delta[n]$$



$$= 0z^{-2} + 0z^{-1} + \underbrace{1z^0}_{=1} + 0z^1 + \dots = 1$$

Z- transform properties:

1.- linearity: $x_3[n] = x_1[n] + x_2[n]$

$$X(z) = X_1(z) + X_2(z)$$

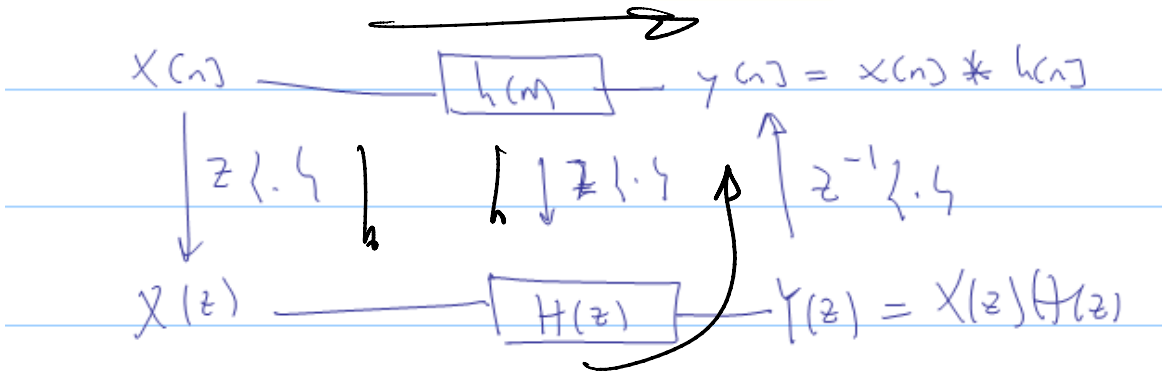
2.- Convolution property

$$y[n] = x[n] * h[n]$$

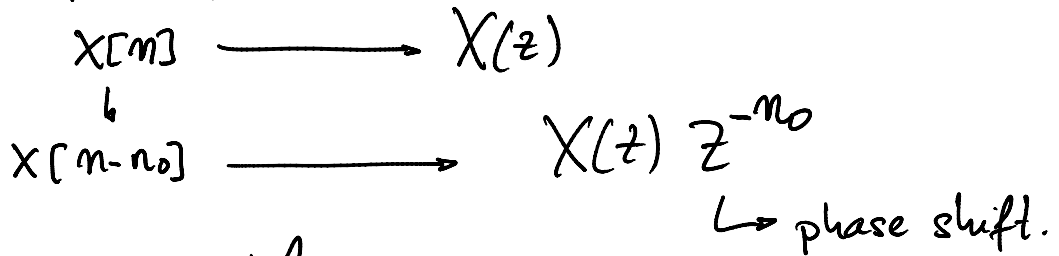
$$Y(z) = X(z) \cdot H(z)$$

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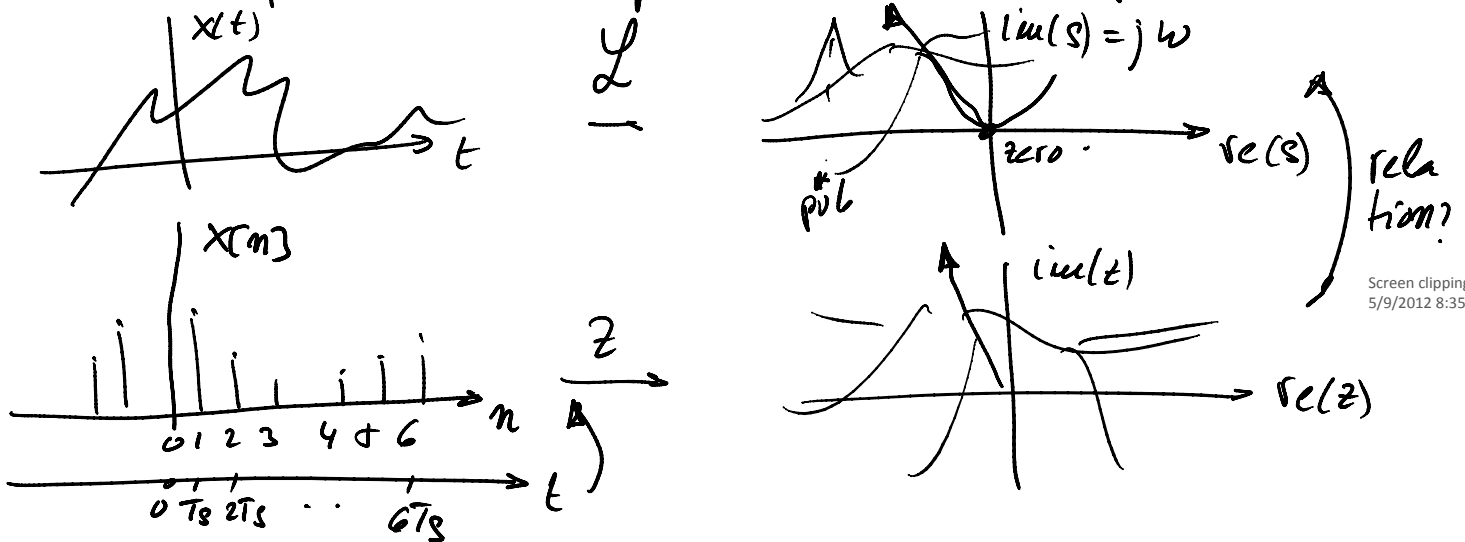
INDIRECT Convolution



3.- Time shift property.



4.- Transformation Laplace \rightarrow Z-transform.



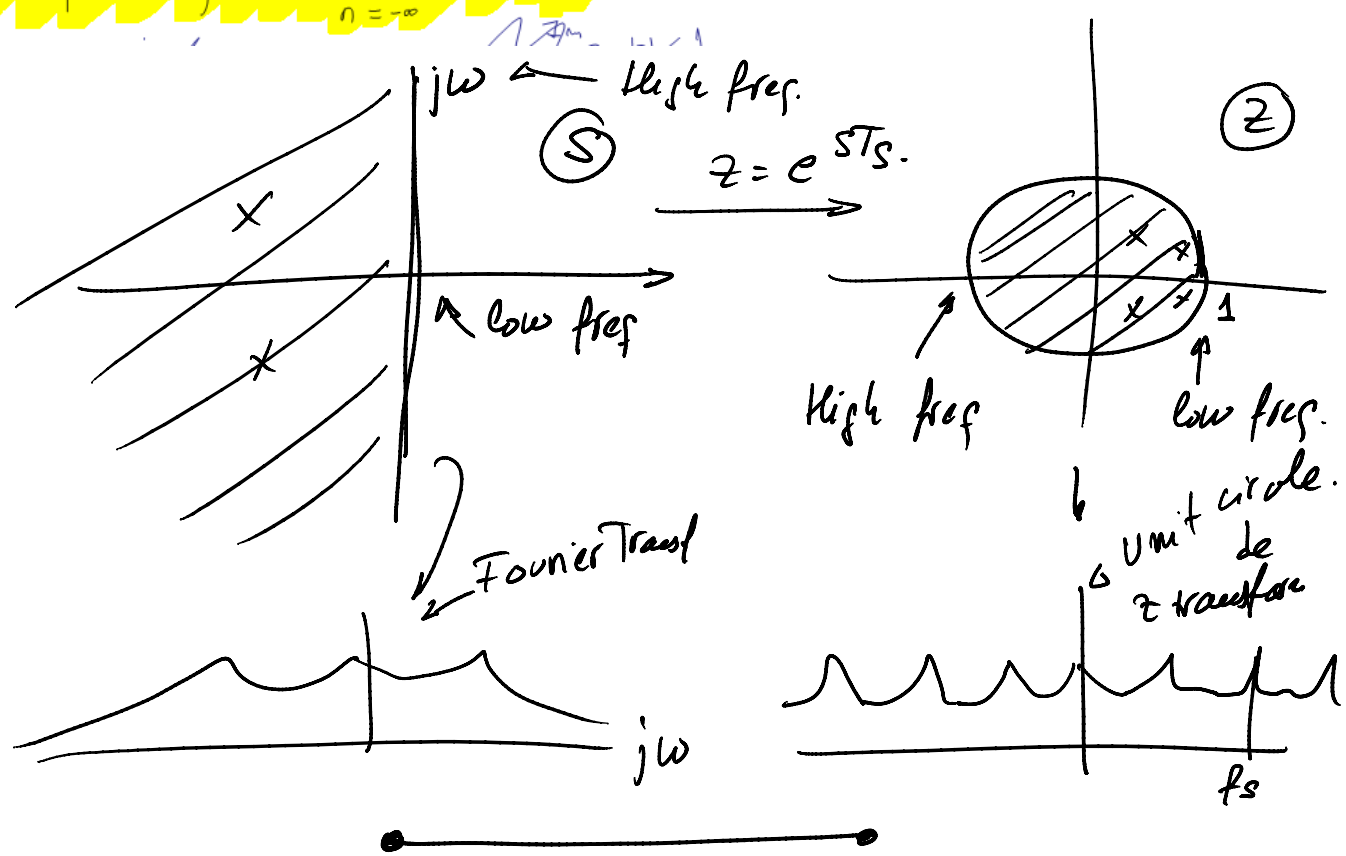
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$$\mathcal{L}\{x_s(t)\} = \sum_{n=-\infty}^{\infty} x(nT_s) e^{-sT_s n}$$

$$\mathcal{Z}\{x[n]\} = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

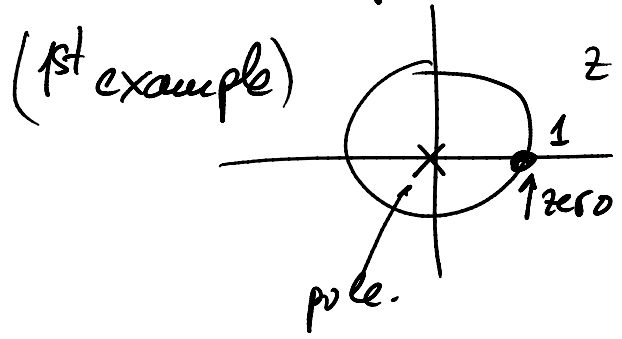
$z = e^{sT_s}$

$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$



Relationship of z-transform, $h[n]$ impulse resp, and block diagram.

• When designing a FIR filter (no feed back).



a) I want LPF.

$$H(z) = \frac{(z-1)}{(z-0)} = \frac{z-1}{z} = 1 - \frac{1}{z} = 1 - z^{-1}$$

b) $h[n] \rightarrow$ Inverse z-t of $H(z)$

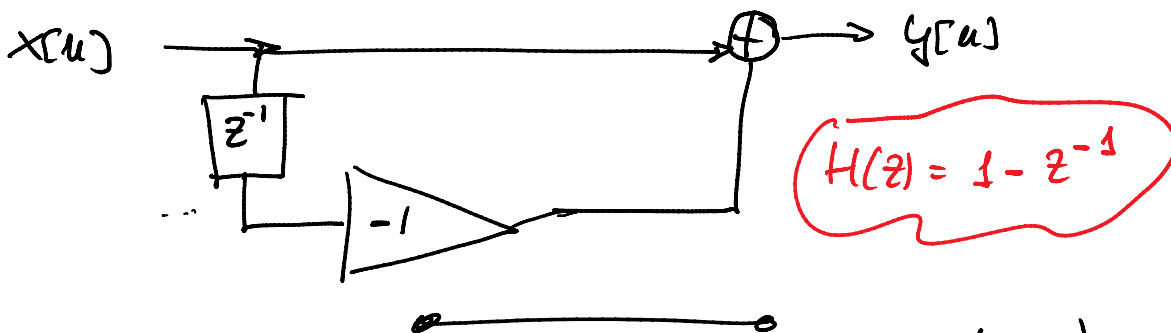
$$h[n] = \delta[n] - \delta[n-1]$$

c) block diagram.

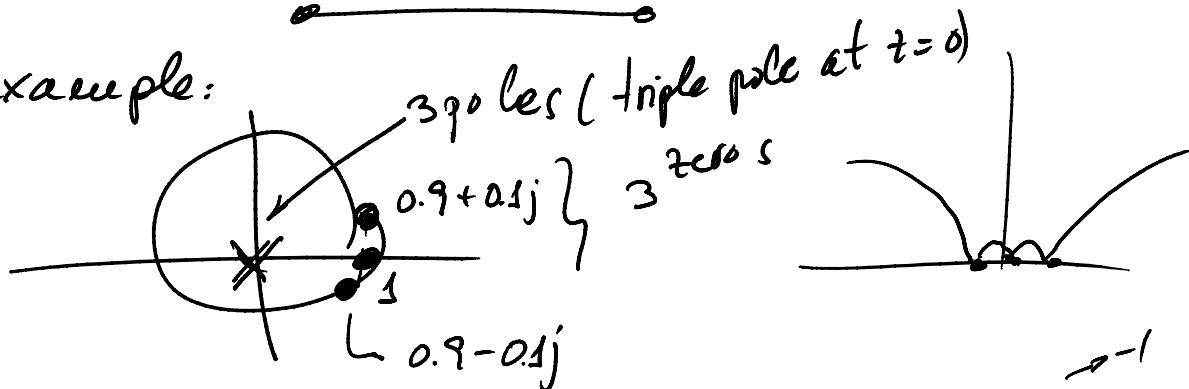
ca) Obtain $y[n] = x[n] - x[n-1]$

$$h[n] = \delta[n] - \delta[n-1]$$

c) Block diagram.



Second example:



$$a) \quad H(z) = \frac{(z-1)(z-0.9-0.1j)(z-0.9+0.1j)}{z^3} = \frac{-0.1^2 j^2 = 0.1^2}{z^3}$$

$$= \frac{(z-1)(z^2 - 2 \cdot 0.9z + 0.1jz - 0.1jz - 0.1j(0.1j) + \frac{-0.9}{0.1j})}{z^3}$$

$$= \frac{(z-1)(z^2 - 1.8z + 0.1^2)}{z^3} =$$

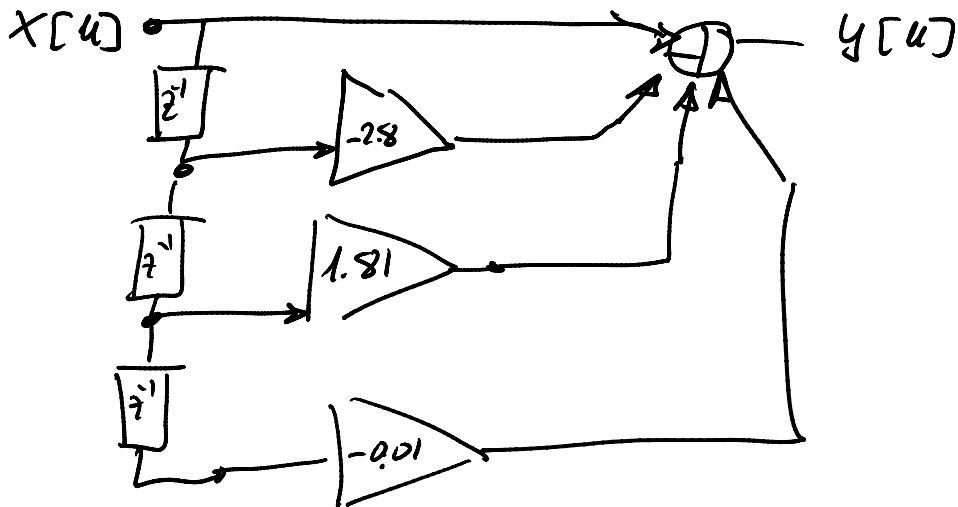
$$= \frac{z^3 - 1.8z^2 + 0.01z - z^2 + 1.8z - 0.01}{z^3}$$

$$= \frac{z^3 - 2.8z^2 + 1.81z - 0.01}{z^3}$$

$$h[n] = 1 - 2.8z^{-1} + 1.81z^{-2} - 0.01z^{-3}$$

$$2) \quad h[n] = \delta[n] - 2.8\delta[n-1] + 1.81\delta[n-2] - 0.01\delta[n-3]$$

$$y[n] = \underbrace{x[n]} - 2.8 \underbrace{x[n-1]} + 1.81 \underbrace{x[n-2]} - 0.01 \underbrace{x[n-3]}$$



Filters with out feed back are not too good
 Next day we will study IIR filters (feed back)