

# EE 1130

## Freshman Eng. Design for Electrical and Computer Eng.

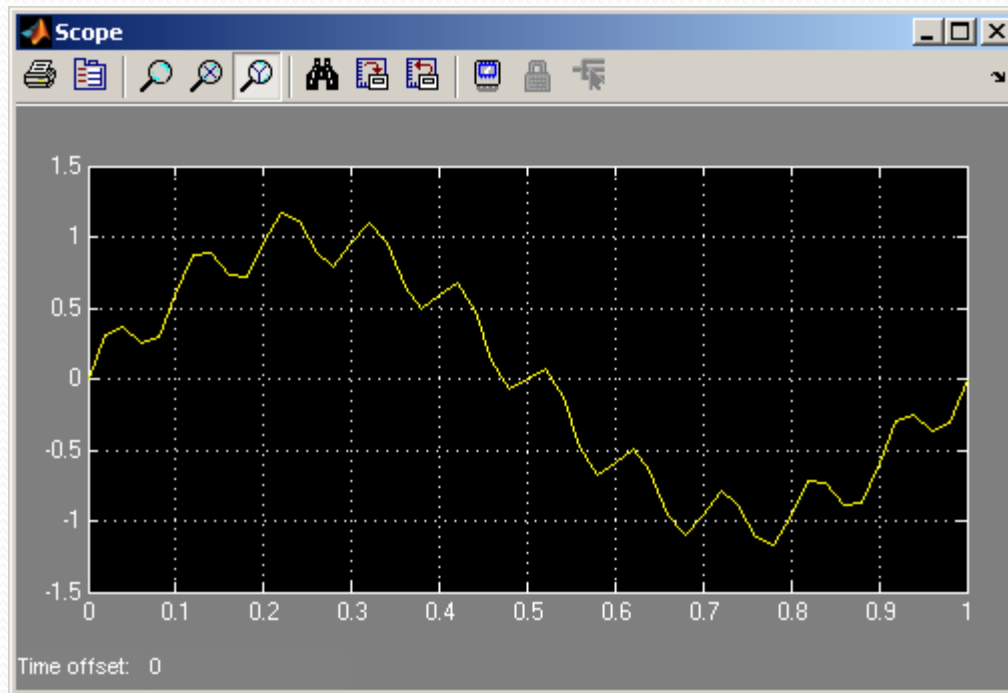
Class 4

Signal Processing Module (DSP).

- Matlab and Simulink.

# Simulink: Signal Processing.

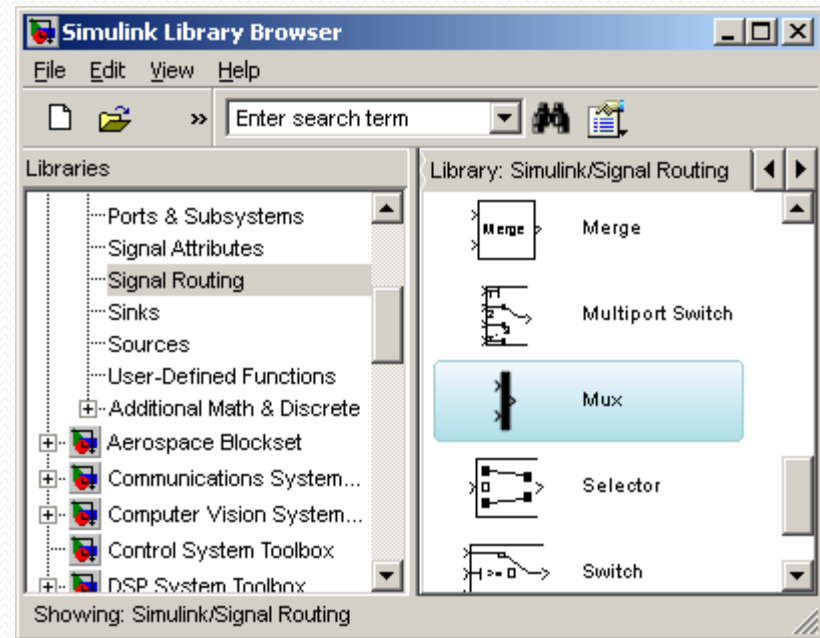
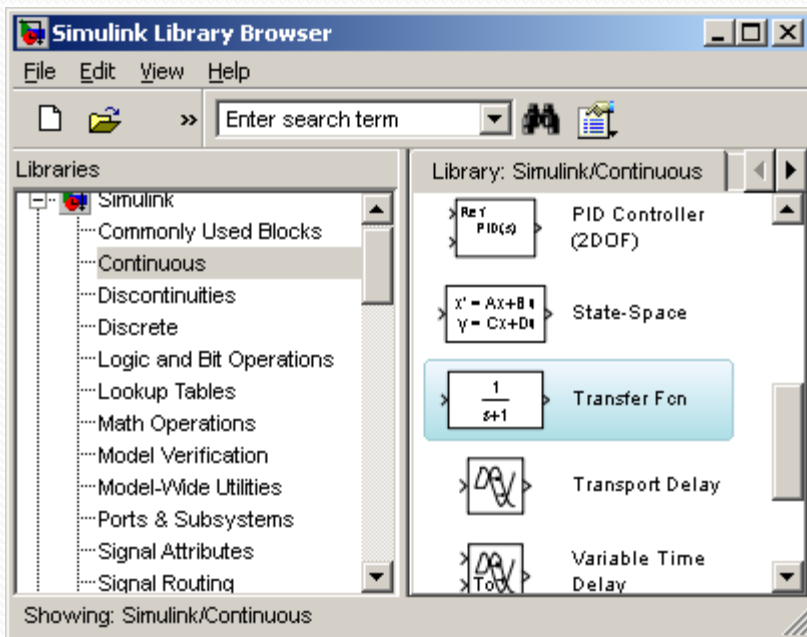
- Last lecture we ended up with a noisy signal as next figure shows:



$$x(t) = \sin(2\pi 1t) + 0.2 \sin(2\pi 60t)$$

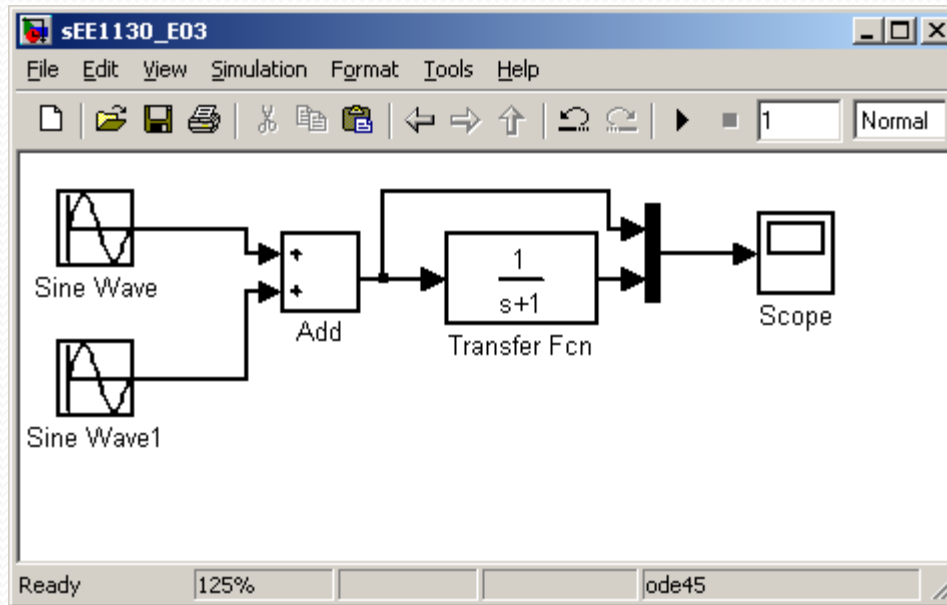
# Simulink: Signal Processing.

- We will insert a system that will filter out the ripple.
- First option is to insert from the continuous library group a Transfer Function block.
- We also add a Mux from Signal Routing library group.



# Simulink: Signal Processing.

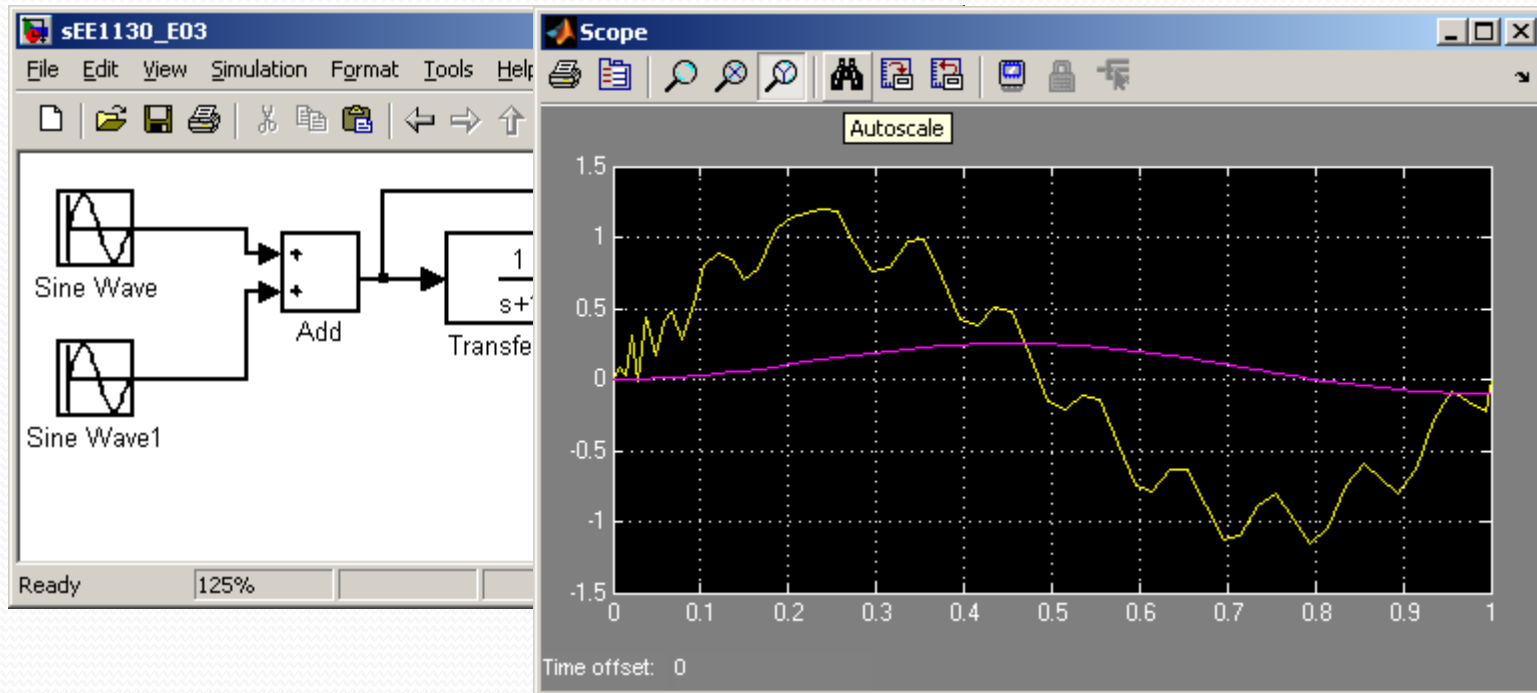
- We insert the Transfer Function after the summator and before the Mux.
- The Mux will allow the Scope to show two traces:



- Now, hit play and see:

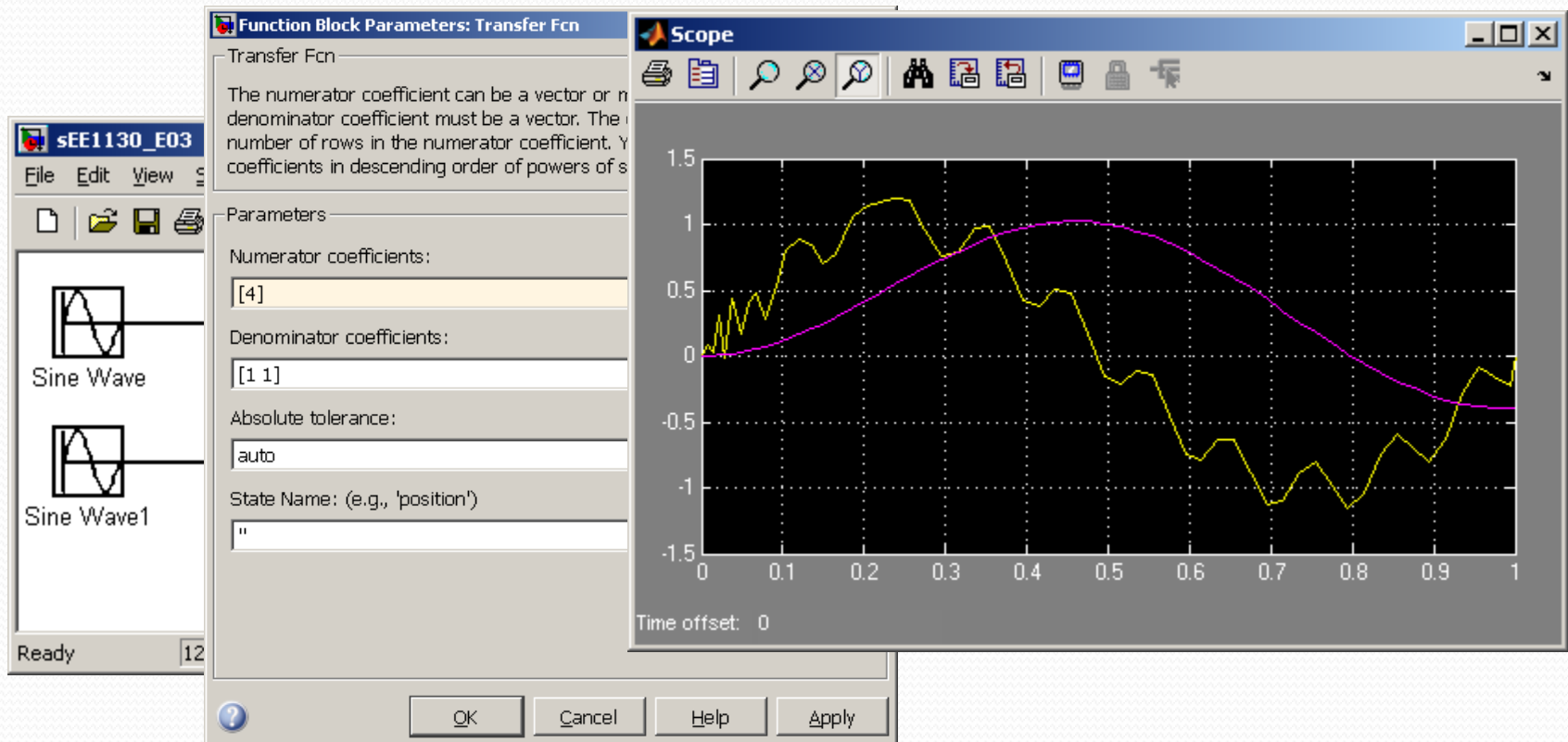
# Simulink: Signal Processing.

- Now, hit play and see:
- Somehow we cleaned the signal, but we need to amplify its gain by a factor of 4. We open the transfer function and set 4 the numerator to do this.



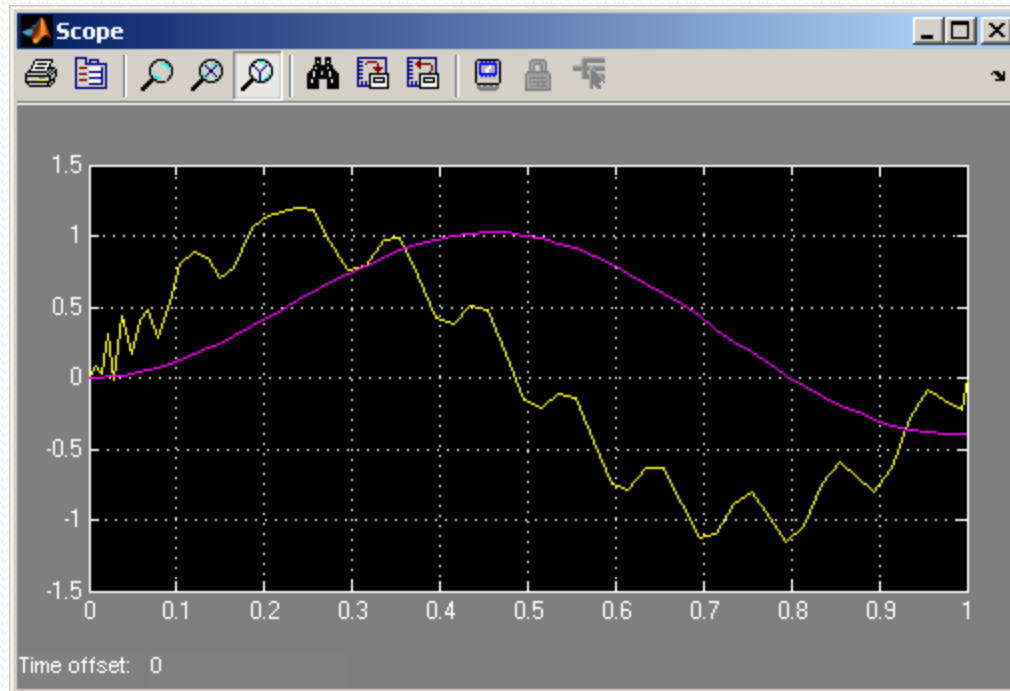
# Simulink: Signal Processing.

- Somehow we cleaned the signal, but we need to amplify its gain by a factor of 4. We open the transfer function and set 4 the numerator to do this.



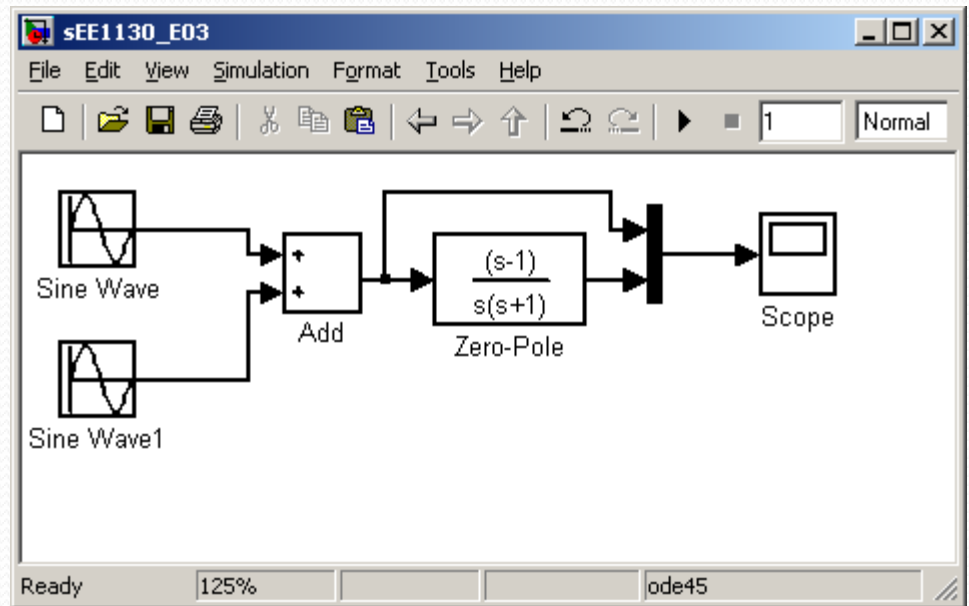
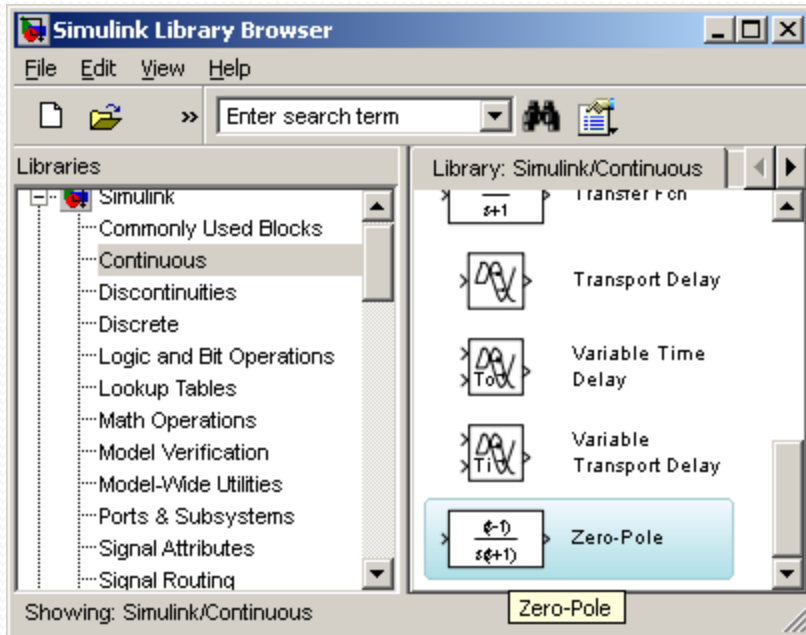
# Simulink: Signal Processing.

- We have cleaned the signal, but introduced a time delay (time shift). This is common in any kind of filters.



# Simulink: Signal Processing.

- Now, lets design a filter that particularly eliminates the signal of 60Hz. We do that using the Zero-Pole Transfer function





# Simulink: Signal Processing.

- When studying Filter Theory you will learn that the roots of the numerator (called zeros) must be  $s=2\pi 60j$  where 60 is the frequency to eliminate at the output.

# Simulink: Signal Processing.

- But the coefficients of the numerator are some of the values of the Electrical Components.
- Remember, for the RC circuit we had:

$$H(s) = \frac{1}{s + 1/\tau}$$

$$Y(s) = \frac{1}{s + 1/\tau} X(s)$$

$$Y(s)s + \frac{1}{RC} Y(s) = X(s)$$

$$\frac{dy}{dt} + \frac{1}{RC} y(t) = x(t)$$

# Simulink: Signal Processing.

- But the coefficients of the numerator are some of the values of the Electrical Components or amplifier gains.
- Therefore we can not have imaginary coefficients, that in fact are component values or amplifier gains.
- We need to do a mathematical trick to convert imaginary numbers into real numbers!!
  - **COMPLEX CONJUGATE**
  - $(a + jb)(a - jb) = a^2 + b^2$  eso es debido a que  $-j^2 = 1$

# Simulink: Signal Processing.

- When studying Filter Theory you will learn that the roots of the numerator must be  $(s-2\pi 60j)$  and  $(s+2\pi 60j)$ . The use of complex conjugated roots is to have real coefficients because:

$$(s - 2\pi 60 j)(s + 2\pi 60 j) = s^2 + 4\pi^2 60^2$$

- At the denominator we just set roots to.

$$(s + 340)(s + 360)$$

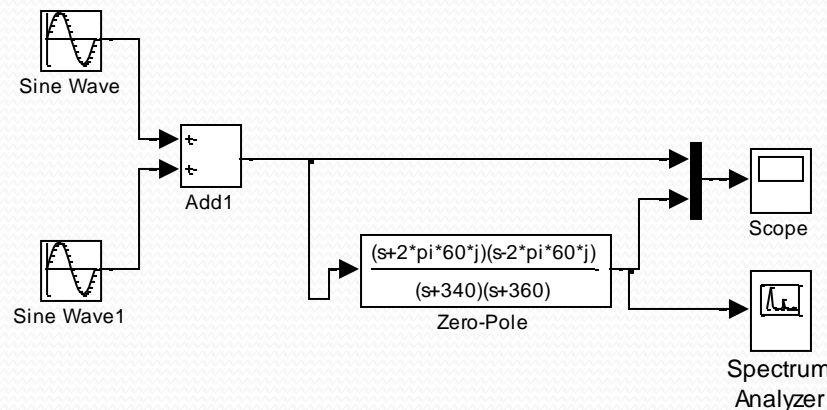
- If you set smaller roots, the output becomes too large. Please try other values to check out by yourself

# Simulink: Signal Processing.

- The final Transfer Function that solve our problem is:

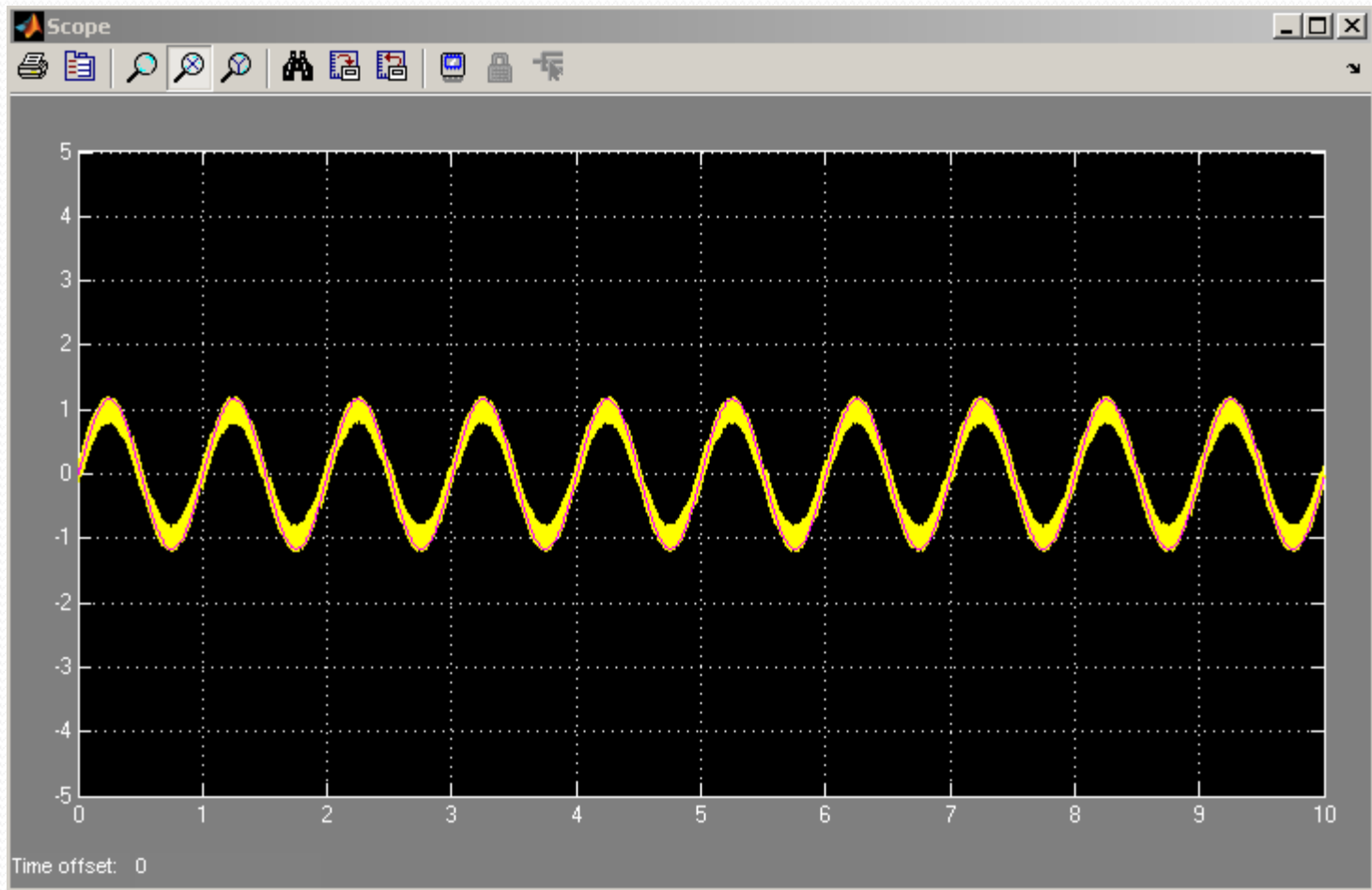
$$H(s) = \frac{s^2 + 4\pi^2 60^2}{(s + 340)(s + 360)}$$

- Now, we simulate this in Simulink



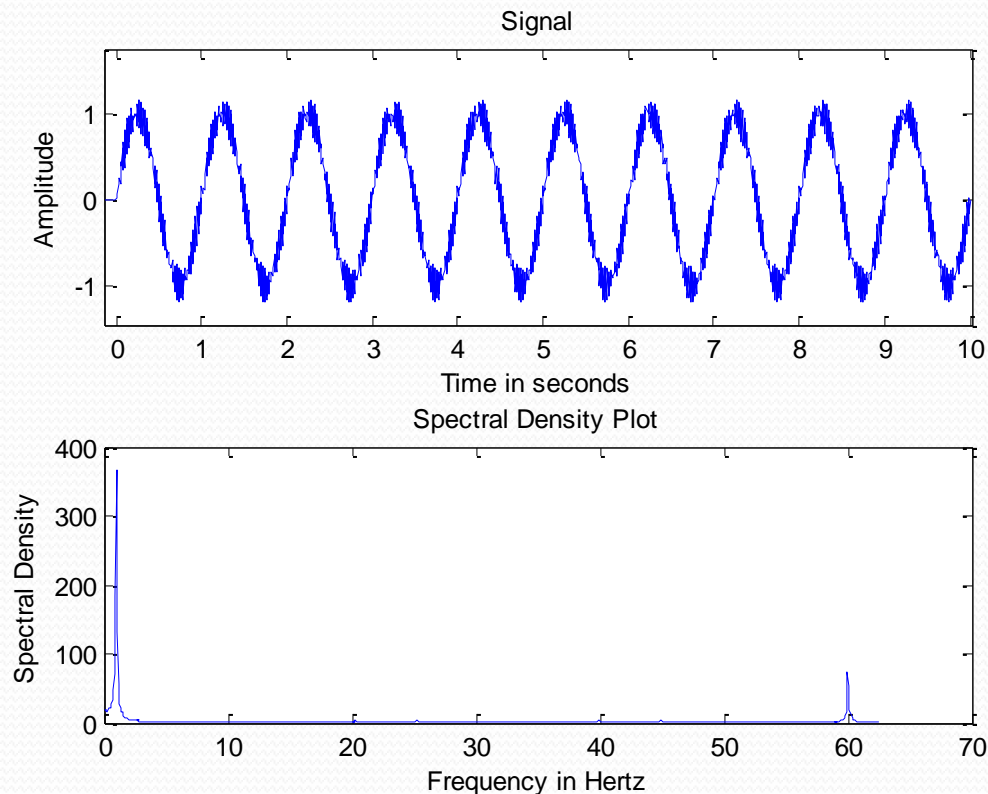
# Simulink: Signal Processing.

- Now we hit play and compare input and output in the Scope



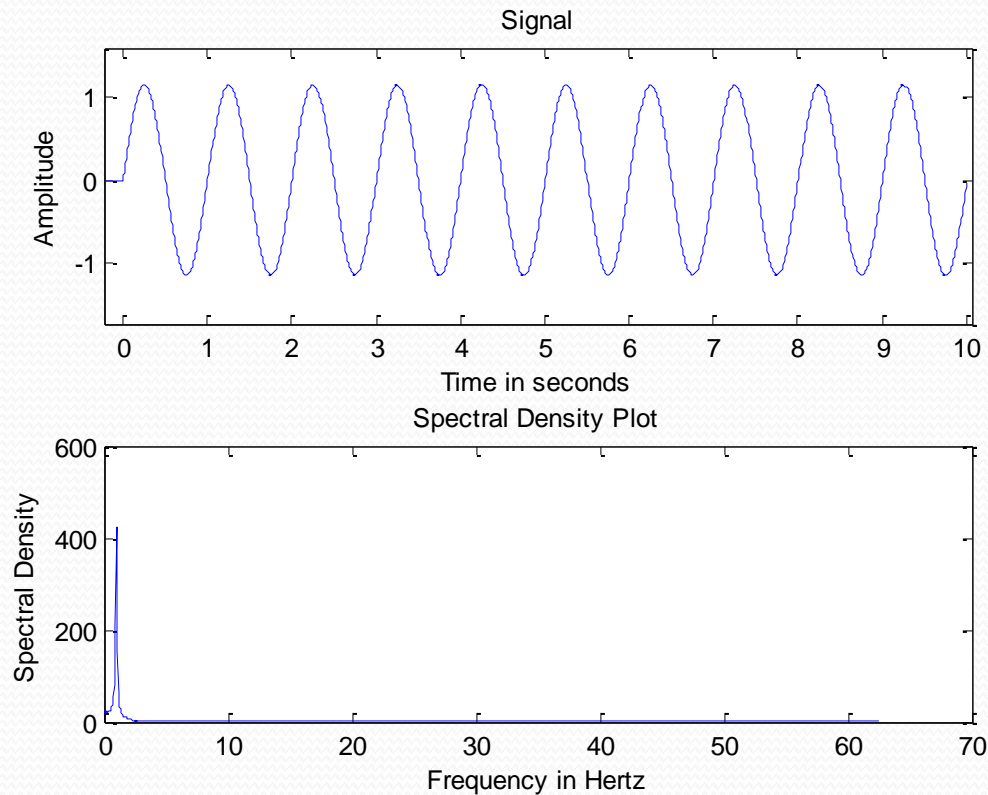
# Simulink: Signal Processing.

- The simulation shows we did the job
  - Spectrum before the filter



# Simulink: Signal Processing.

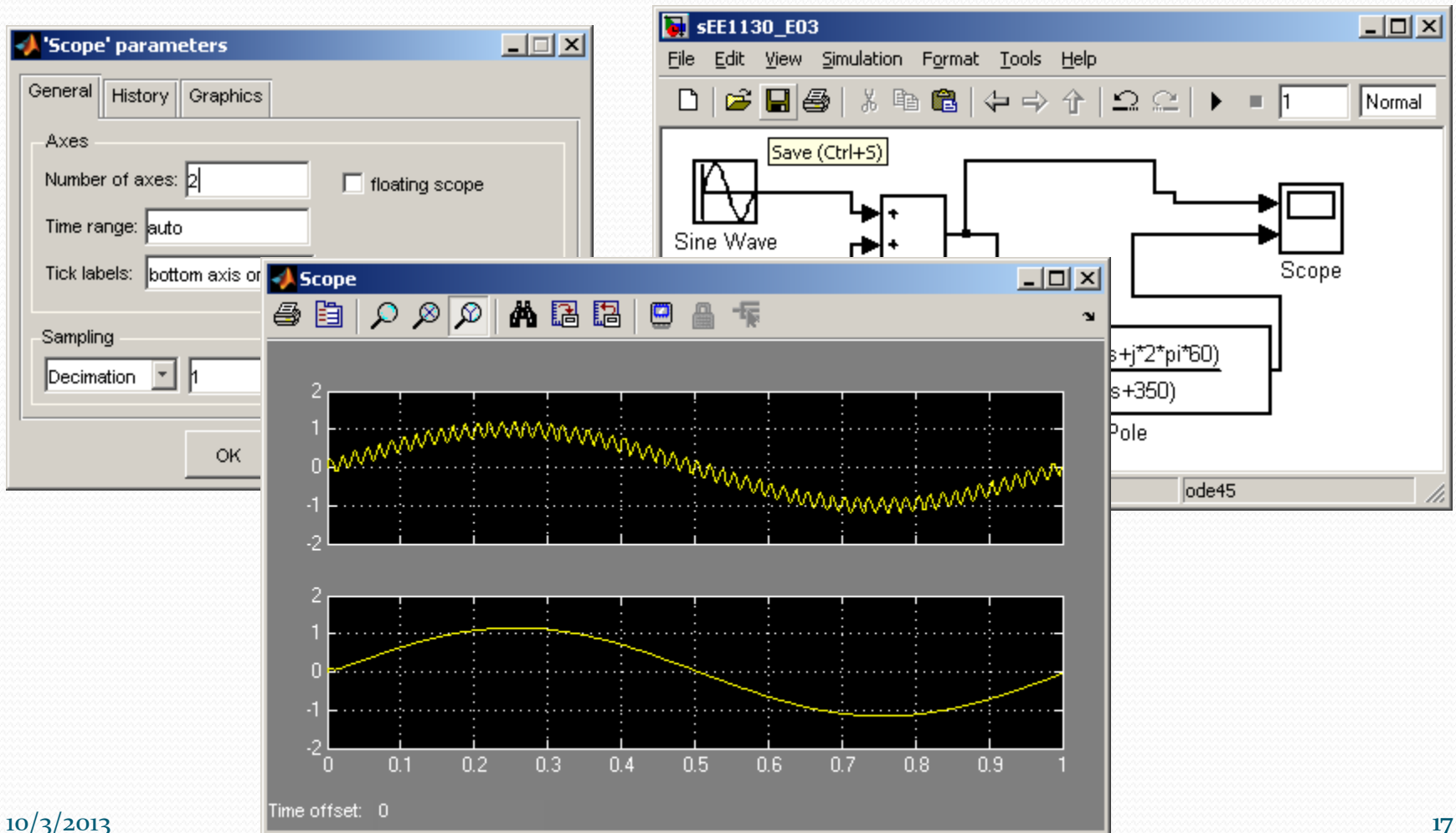
- The simulation shows we did the job:
  - Spectrum after the filter





# Simulink: Signal Processing.

- We notice the dark trace is completely clean of noise. We could add another trace to the scope and see both signals separated:



# Simulink: Signal Processing.

- Once the simulation shows we solved the problem, we need to implement the Electrical Circuit.
- In order to do that, we need to modify the Transfer Function in a sum of simpler Transfer Functions of the type:

$$H_{simple}(s) = \frac{G}{(\tau s + 1)}$$

- This is done with Partial Fraction Expansion:

$$H(s) = \frac{s^2 + 4\pi^2 60^2}{(s + 340)(s + 360)} = \frac{R_1}{s + 340} + \frac{R_2}{s + 360}$$

- Matlab calculate the residues very fast:

# Simulink: Signal Processing.

- Matlab calculate the residues very fast:

$$H(s) = \frac{s^2 + 4\pi^2 60^2}{(s + 340)(s + 360)} = \frac{-1.35861 * 10^4}{s + 360} + \frac{1.2886 * 10^4}{s + 340}$$

# Simulink: Signal Processing.

- One more modification yields:

$$H(s) = \frac{-37.7}{\frac{1}{360}s + 1} + \frac{37.9}{\frac{1}{340}s + 1}$$

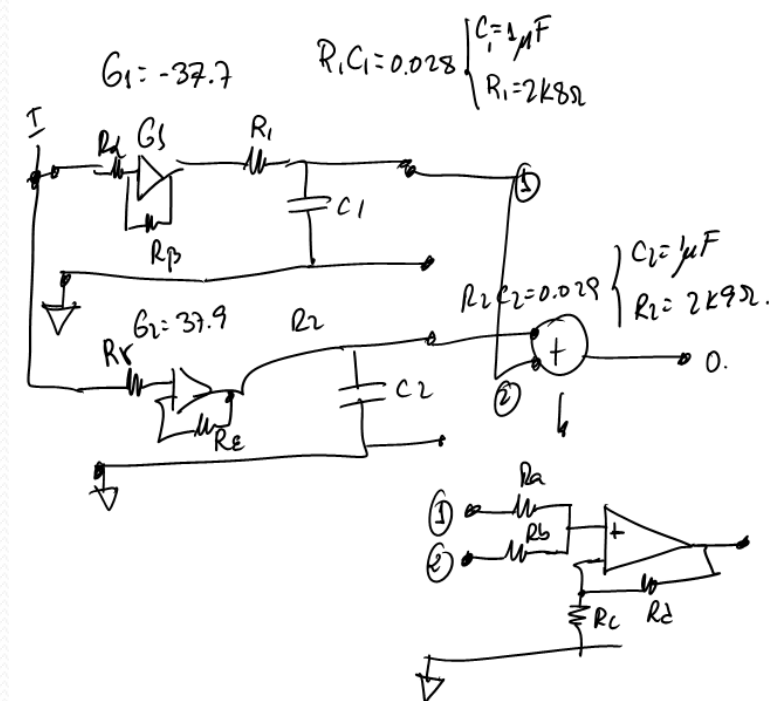
- Each term correspond to a RC circuit:

$$H_{simple}(s) = \frac{G_1}{(R_1C_1s + 1)} + \frac{G_2}{(R_2C_2s + 1)}$$

# Simulink: Signal Processing.

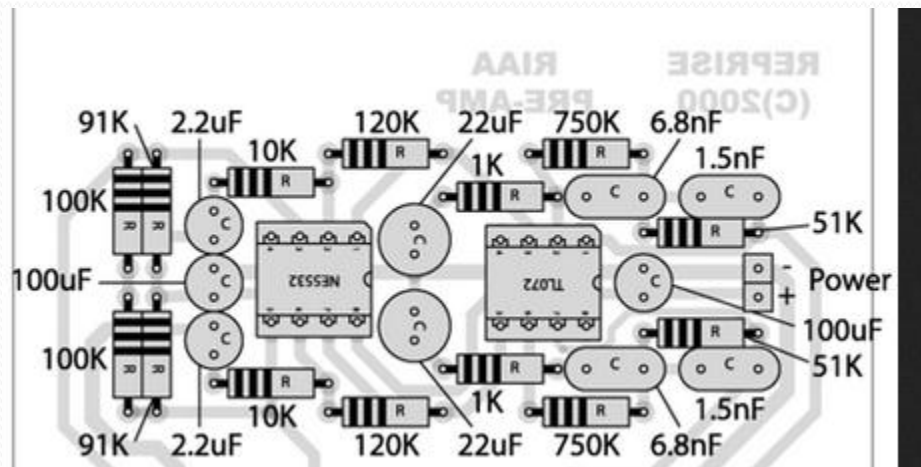
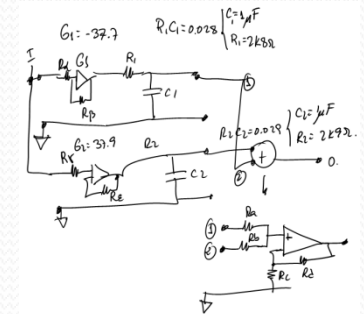
- Implementation:

$$H(s) = \frac{-37.7}{\frac{1}{360}s + 1} + \frac{37.9}{\frac{1}{340}s + 1}$$



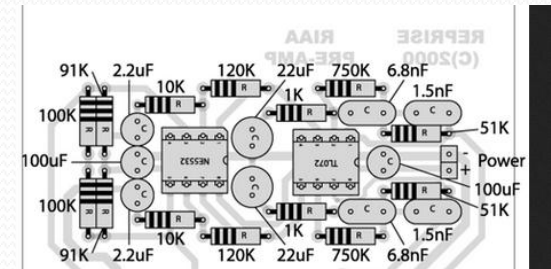
# Simulink: Signal Processing.

- From the Electrical Schematics we build the physical layout:
- We obtain something like:



# Simulink: Signal Processing.

- From the physical layout:
- we build the PCB (Printed Circuit Board)
- We solder the components.
- Solder the cables.
- Then we test!!!



# Simulink: Signal Processing.

- We generate the final report with our findings, to assess that the circuit does what we intended it to do.





# End of Class